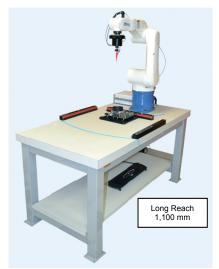


# 6 Axis Electric and Magnetic Near-Field Scanning System



EM-ISight-LR 9kHz to 40GHz Electromagnetic Scanning System Long Reach Model



EM-ISight-LR (Long Reach) EMI/EMC measurement system built on a 6 axis articulated robot designed to support multiple applications and industries including networking, automotive, integrated circuits, aviation, military, and consumer products. Used as compliance system for IEC-61967-1-6 or a pre-compliance / development tool, the abundance of features meet most requirements for research, design and analytical needs. Customizable features allow the end user to have complete control of the solution. System includes a workstation which allows for integration of the robot and controller. Multiple work space including off axis horizontal and vertical assessments can be conducted. Multiple probe options are available for the system and the ability to upgrade for ESD measurements at a later date provides a fully flexible test platform. Near-field measurements can be executed from 9 kHz to 40GHz as standard. EM-ISight-LR has the best reach for automated near-field scanning solutions with the ability to scan systems as large as 1,000 mm x 1,000 mm Cartesian and over 2,000 mm x 600 mm off axis, this solution has the ability to conduct a scan on a complete fully assembled rack system.

EM-ISight-LR is an affordable and easy to use system with great return on investment when compared to traditional measurement solutions. Using the optional Far Field Approximation (FFA) module is an alternative to costly pre-compliance EMC chambers which have high maintenance costs and use significant floor space. Integration of high end Low Noise Amplifiers at the core of the transmission line yield low insertion loss and high unwanted field rejection of better than 25dBm. Easy setup for measurement profiles (less than 60 seconds) using the optional vison camera and touch detection allow complex topologies of a PCB to be taught in real time.

Measurements can be conducted in traditional Cartesian and off axis Horizontal scan configurations.

### **Applicable Standards**

IEC-61967-1-6 VCCI/CISPR 22/FCC Pt 15/22 EN55022 CISPR 12/FCC Pt 18/EN55011/ EN60555/VDE0871 EN55024/EN6100-6-4/GR-1089-CORE ITU-T/ETS300/ IEC-6100-3

# Y (mm)

#### **Applications**

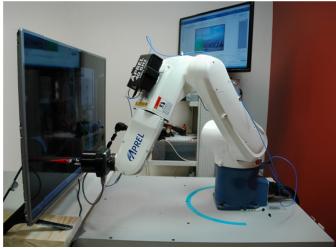
Susceptibility / ESD Consumer products cell phone/computer devices Integrated Circuit/Printed Circuit Board Wireless modules De-Sense testing (receiver circuits) Medical devices Automotive, aviation and satellite Enterprise solutions Electronic device emissions Pre-Compliance testing (emissions/susceptibility) Quality control/audit

## Supported Spectrum Analyzers

Tektronix Keysight/Agilent Anritsu Rhode and Schwartz

NOTE: Signal generator, spectrum analyzer is customer supplied.

Some applications require additional upgrades from a standard package spectrum analyzer; please confirm spectrum analyzer compatibility with APREL.



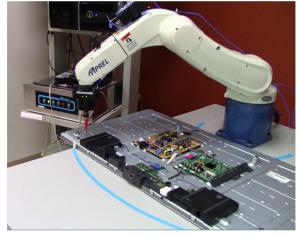




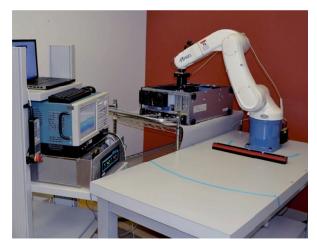
**Front Workspace Cartesian** 

# **System Configuration**

- Denso RC8 Controller
- Configurable for 9kHz to 6GHz/20GHz/40GHz
- Single probe solution from 9kHz to 40GHz
- X/Y/Z scan areas of 1,000 mm (Cartesian)
- High resolution scan (>0.07 mm) based on repeatability error
- Coarse scan with dynamic peak search function
- Real-time topology analysis using vision and dynamic touch detection (Cartesian)
- Z height distance from 0.07 mm up to 900 mm (Cartesian)
- 4D Measurements of DUT by integrating X/Y/Z & Phi
- Field distribution presented in 2D, 3D or 4D plotting with quick snap image processing
- Source direction plots (vector)
- Customizable reports based on user requirements automatically exported to MS Word
- Delta plot measurement function (compare before/after measurements)
- Frequency distribution plots based on span and trace with added limit lines
- AVI export function for real-time visualization of field and frequency distribution
- · Advanced measurement functions, single point analysis, quick check, free move and point delta
- Micro Strip Line 9kHz to 6GHz/20GHz/40GHz
- Quick scan setup using vision system

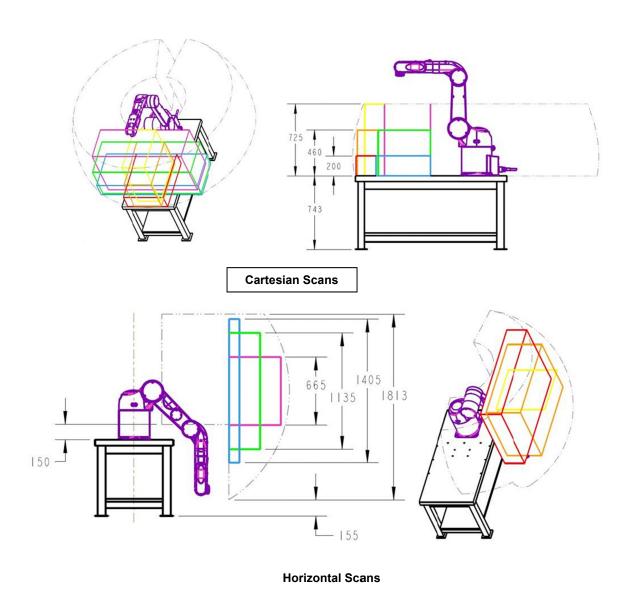


**Front Workspace** 



Side workspace

# **Optional Workstation Configurations**

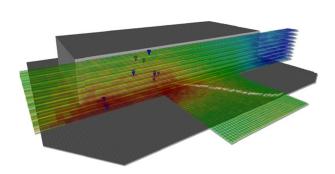


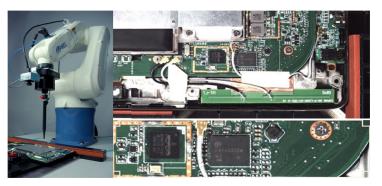
Values presented are nominal for single axis motion.

NOTE: Workstation must be secured to the floor with the Long Reach system.

#### **Optional Accessories/Software**

- Exy 1.5mm E-Field Antenna Probe
- Hz-Field Antenna Probe
- 10Hz to 1MHz low Frequency H-Field Probe
- Dual Stage Low Noise Amplifiers DC to 6/20/40 GHz
- FFA Far Field Approximation Software
- USA Ubiquitous Server Application
- ESD/Susceptibility Test Suite
- Advanced device positioner
- 7 Axis ESD Device Positioner
- 3 x 4 Meter EMC Shield Room



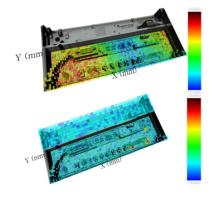


4D Plot with Interpolation

**Vision System Zoom Function** 

### **Standard System Configuration**

- Denso VM-60B1G with RC8 Controller
- Single probe solution for measurements from 9kHz to 6GHz/20GHz/40GHz
- Low Noise Amplifier 9kHz to 6GHz
  - Optional Low Noise Amplifier 100MHz 20GHz
  - Optional Low Noise Amplifier 100MHz 40GHz
- Calibrated H-Field antenna probe to ISO/IEC-17025 standards to IEC-61967-1-6
- Software platform with 1 year fully comprehensive support and feature updates
- Software supports user defined parametric settings, user defined pass/fail graphing, and graphical
  measurement data for statistical readout full 3/4D graphic package for visualization and manipulation of
  measured fields, storage and retrieval of measurement results
- Remote access to measurement database
- Dynamic process control
- Z-Axis device topology surface detection system
- Standard workstation L = 152 cm x W = 76 cm x H = 30cm (larger options available) 230 cm robot mounted
- Collision detection system for user/DUT safety
- · Device Positioning fixture
- Vision System



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Vision System	Custom designed software 10.7 MP CCD camera, Low	for Vision Integration distortion lens, real-time image capture, Permanent Robot mount +/-
	180 rotation, Lens and Robot Calibration in X/Y, Autofocus and Zoom Feature, control Brightness, Contrast and Saturation and export file to XML	
Software	Windows 7, 8, 10 and MAC	
	User friendly GUI that allows for easy setup and data retrieval	
	Automatic antenna probe movement control	
	Automatic system control or user definable parametric setup incorporating optional vision camera Visual display including storage and retrieval of measured results in full 3/4D	
	Data tracking for project improvement/quality control	
	Importation of previous measurement profiles to track design/quality improvements	
	Vision system control for re	
Applications	Advanced measurement plan	tform for Large Device Under Test 1,000 x 1,000 mm
		pise emission analysis
		ing placement/optimization
		pard or IC design optimization/placement na design optimization
		munity/emitted radiation analysis of mobile handset LCD or LCD
	control	
	•	al Susceptibility and ESD test modules
	Far Field Approxi	imation (additional software required)
Typical Probe Measuring Unit	Antenna:	E or H-field with 0.02mm spatial resolution
	Typical frequency range:	Frequency sweep, in band discreet value from 10KHz to 40GHz
	Sensitivity:	Probe Dependent
	VSWR:	<1:2
	Input impedance:	$50\Omega$ Normalized
	Linearity:	<0.1dB 100MHz to 40GHz, Gain 31dBm NE 4 0dB
	LNA (standard): LNA (Optional)	100MHz to 40GHz, Gain 31dBm NF 4.0dB 30dB Preamplifier for EM Measurements from 10kHz to 6GHz
	Noise floor:	Measured with MSL @ 1GHz = -139dB with *preamplifier module
	Noise noor.	Optional GPS Probe @ 1.6GHz = -151dBm*
	Measurement Uc:	0.05dBm @ 0.05mm Z and 0.1dBm @ 0.2mm X & Y
	Optional probes:	Rosenberger Micro-Coax rectangular and small loop and interface
Measuring Reach and	NO. of axes: 6 (X, Y, Z and	d θ)
Movement	Typical reach*:	
	Along X & Y axes:	1,000 mm x 1,000 mm (Cartesian) up to 2,200 mm off Axis
	Along Z axis:	900mm (Cartesian) up to 750mm off Axis
	Rotation $\theta$ axis:	360°
	Resolution: X and Y axes:	0.07mm
	Z axis:	0.07mm
	θ axis:	0.1°
	Alignment accuracy:	0.1
	X and Y axes:	0.07mm
	Z axis:	0.07mm
	θ axis:	± 1°
		surement space (reach) are available.
DUT Orientation		surement space (reach) are available.  Horizontal
DUT Orientation	Options to increase mea	surement space (reach) are available.  Horizontal  Vertical
	Options to increase mea Typical:	Horizontal Vertical Custom
	Options to increase mea Typical:  Controller for overall control	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM
	Options to increase mea Typical:	Horizontal Vertical Custom  DI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10
	Options to increase mea Typical:  Controller for overall contro Operating system:	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM
System Control	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller:	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port
System Control	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature:	Horizontal Vertical Custom  Ol: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  0° C to +28°C
System Control	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity:	Horizontal Vertical Custom  Ol: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  0° C to +28°C 40% or less
System Control	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input:	Horizontal Vertical Custom  Ol: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz*
System Control	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption:	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA
System Control	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight:	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg
System Control  General	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension:	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm
System Control  General	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg
System Control  General	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s Automated peak search	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm  single report including layers, rotations and frequency distribution
System Control  General	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s Automated peak search DUT teaching using Vison S	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm single report including layers, rotations and frequency distribution  System along with XML data exportation
System Control  General	Options to increase mea Typical:  Controller for overall contro Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s Automated peak search DUT teaching using Vison S Dynamic touch detection an	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm single report including layers, rotations and frequency distribution  System along with XML data exportation and vision control for 3D DUT teaching
System Control  General	Options to increase mea Typical:  Controller for overall control Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s Automated peak search DUT teaching using Vison S Dynamic touch detection an User defined plotting for m	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm single report including layers, rotations and frequency distribution  System along with XML data exportation and vision control for 3D DUT teaching ultiple scan locations
System Control  General	Options to increase mea Typical:  Controller for overall control Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s Automated peak search DUT teaching using Vison S Dynamic touch detection at User defined plotting for m Limit exceed search function	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm single report including layers, rotations and frequency distribution  System along with XML data exportation and vision control for 3D DUT teaching ultiple scan locations on & User defined limit function
System Control General	Options to increase mea Typical:  Controller for overall control Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s Automated peak search DUT teaching using Vison S Dynamic touch detection at User defined plotting for m Limit exceed search functio Optional Far Field Approxim	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm Single report including layers, rotations and frequency distribution  System along with XML data exportation and vision control for 3D DUT teaching ultiple scan locations on & User defined limit function mation for EMC test equivalent sites of 3M and 10M
DUT Orientation  System Control  General  Additional Features SW	Options to increase mea Typical:  Controller for overall control Operating system: Motor controller: Measuring interface:  Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s Automated peak search DUT teaching using Vison S Dynamic touch detection at User defined plotting for m Limit exceed search functio Optional Far Field Approxim Ubiquitous Server Applicati	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm  single report including layers, rotations and frequency distribution  Osystem along with XML data exportation and vision control for 3D DUT teaching ultiple scan locations on & User defined limit function mation for EMC test equivalent sites of 3M and 10M ion for custom development of test applications
System Control General	Options to increase mea Typical:  Controller for overall control Operating system: Motor controller: Measuring interface: Operating requirement: Temperature: humidity: AC power input: Power consumption: Weight: Workstation Dimension: Multiple plots recorded in s Automated peak search DUT teaching using Vison S Dynamic touch detection at User defined plotting for m Limit exceed search functio Optional Far Field Approxim	Horizontal Vertical Custom  OI: PC with Intel i5 or better processor and 8GB RAM Windows 7/8/10 Denso RC8 GPIB/LAN/Serial port  O° C to +28°C 40% or less Three phase 200V ~ 230V, 50Hz/60Hz* 1.8 kVA Controller = 22kg, Robot = 88kg, Workstation 70kg L = 1,500 mm x W = 760 mm x H = 300 mm  ingle report including layers, rotations and frequency distribution  System along with XML data exportation and vision control for 3D DUT teaching ultiple scan locations on & User defined limit function mation for EMC test equivalent sites of 3M and 10M ion for custom development of test applications reporting